



Making roads safer
for drivers,
passengers, and
pedestrians

VRU solution – pitch deck



Legal notice

This investor deck contains forward-looking statements within the meaning of the safe harbor provisions of the Private Securities Litigation Reform Act of 1995. All statements other than statements of historical fact in this deck are forward-looking statements, including but not limited to, the ability of SaverOne's technology to substantially improve the safety of drivers; SaverOne's planned level of revenues and capital expenditures; SaverOne's ability to market and sell its products; SaverOne's plans to continue to invest in research and development to develop technology for both existing and new products; SaverOne's intention to advance its technologies and commercialization efforts; SaverOne's plan to seek patent, trademark and other intellectual property rights for our products and technologies in the United States and internationally, as well as its ability to maintain and protect the validity of its currently held intellectual property rights; SaverOne's expectations regarding future changes in its cost of revenues and our operating expenses; interpretations of current laws and the passage of future laws; acceptance of SaverOne's business model; the ability to correctly identify and enter new markets; the impact of competition and new technologies; general market, political and economic conditions in the countries in which SaverOne operates; projected capital expenditures and liquidity; SaverOne's intention to retain key employees, and our belief that we maintain good relations with all of its employees; any resurgence of the COVID-19 pandemic and its impact on SaverOne's business and industry; security, political and economic instability in the Middle East that could harm SaverOne's business, including due to the current war between Israel and Hamas; and other risks and uncertainties, including, but not limited to, the risks detailed in the Company's Annual Report on Form 20-F filed with the U.S. Securities and Exchange Commission (the "SEC") on March 25, 2024 and in subsequent filings with the SEC. The Company's filings are available on its website at www.sec.gov. These forward-looking statements involve known and unknown risks and uncertainties and are based on current expectations, assumptions, estimates and projections about the Company and the industry. The Company undertakes no obligation to update forward-looking statements to reflect subsequent occurring events or circumstances, or to changes in its expectations, except as may be required by law. Although the Company believes that the expectations expressed in these forward-looking statements are reasonable, it cannot assure you that its expectations will turn out to be correct, and investors are cautioned that actual results may differ materially from the anticipated results.

SAVERONE AT A GLANCE



+50

Employees



+20

Diverse IP Portfolio
Registered & Pending



+4000

Installations

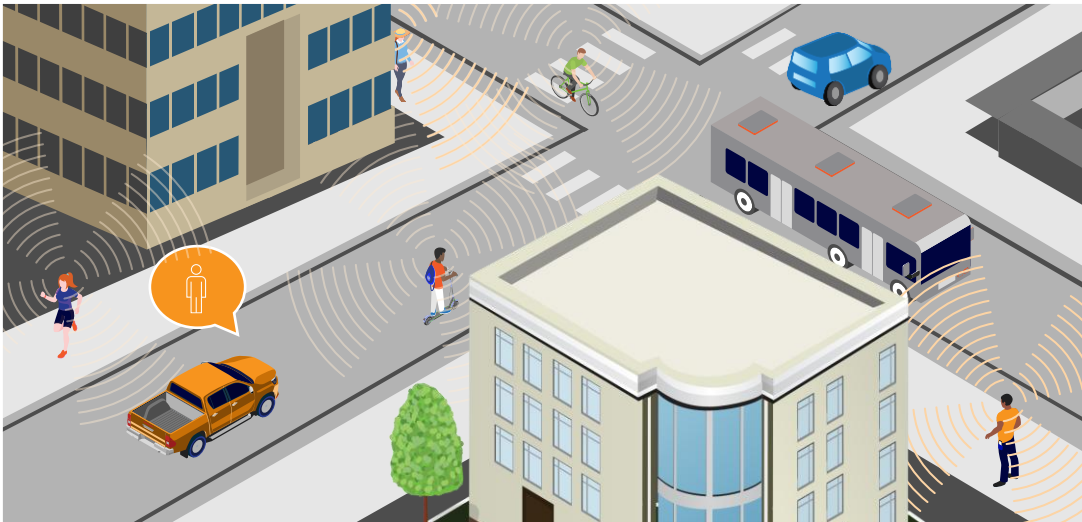


+100

Active Customers

- **Installations** in Europe, USA, Mexico and Asia
- **International** distribution agreements
- **Partnership with Iveco**, one of Europe's largest truck manufacturers
- **Collaboration with Volvo Busses**, one of Europe's largest Bus manufacturers

Our mission is to make roads safer for drivers, passengers, and pedestrians alike – through cellular network-based technological solutions



2 products



Vulnerable Road User safety solution

Detection & localization of Vulnerable Road Users (VRUs) outside the vehicle even in non-line-of-sight (NLOS) and adverse weather conditions through mobile signals

Focus of this pitch

In-cabin driver distraction prevention

Driver safety solution designed to combat distracted driving by identifying and monitoring cell phones located in the driver's vicinity and selectively blocking distracting apps

Our experienced leadership team



Jacob Tenenboim
Chairman

35+ years in technology management & entrepreneurship

Among his exits are:



Ori Gilboa
Chief Executive Officer

25+ years in automotive & retail industries

CEO **JR/DUTYFREE**
JAMES RICHARDSON

CEO **נגב**

Manager **MAYER**
CARS AND TRUCKS CO. LTD



Yossi Cohen
Chief Operating Officer & Co-Founder

20+ years in leading global operations in high-tech areas

Senior Manager of Program Management & Business Operations



Yoav Zilber
Head of Business Development

20+ years in international marketing & business development

VP Business Development Africa



CEO



Aviram Meidan
Vice President Research & Development

20+ years in automotive product development

VP R&D



CTO



Senior Manager



Omri Hagai
Chief Financial Officer

10+ years of experience in financial management of public companies

Director of Finance



Disclosure & Reporting controller



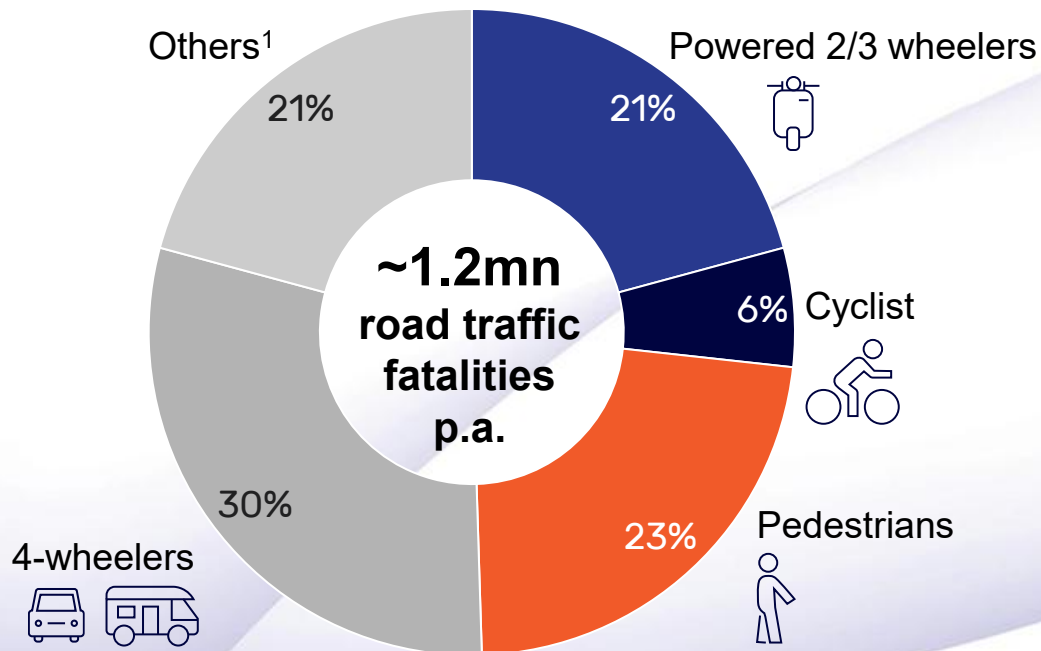
Vulnerable road users (VRU) require special attention & protection

Non-motorised road users such as pedestrians (especially children), cyclists, motor-cyclists and persons with disabilities/ reduced mobility & orientation are unprotected in case of collisions



Despite developments in vehicle safety, vulnerable road users (VRUs) are still at risk today

Distribution of deaths by road user type, globally



- > VRUs account for **~50%** of fatalities
- > Every **53 seconds** a VRU dies on the road
- > Already slight injuries cost **~6.3k USD** per injury²
- > Serious injuries cost **~140k USD** per injury²
- > **~5bn USD** total injury cost in Germany annually³

1. Occupants of vehicles carrying more than 10 people, heavy goods vehicles and "other" users

2. Average cost of road-traffic injuries in Germany

3. ~160k VRU injuries in road traffic in Germany 2019

While the industry is aware of the issue, current solutions cannot detect VRUs in non-line-of-sight, posing a safety challenge

Existing sensors today...

LiDAR



- + Range, night operation, Distance detection, classifications of objects
- No NLOS¹ detection, weather impact, no color detection



Radar



- + Velocity detection, night operation, weather resistance
- Very limited NLOS¹ detection, no color detection, limited classification



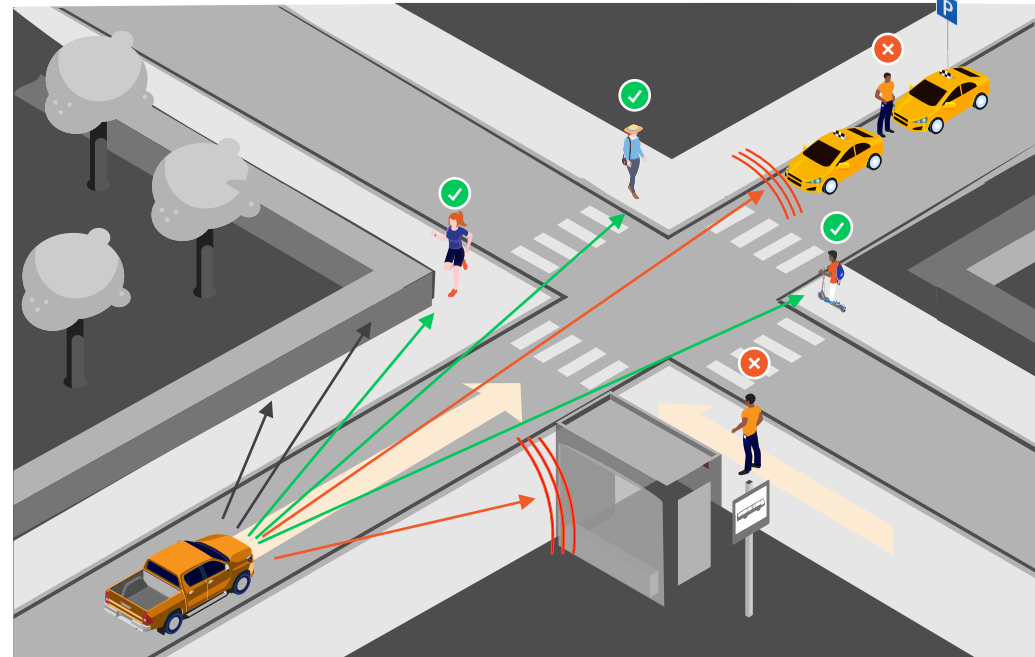
Camera



- + Color detection, object classification
- No NLOS¹ detection, weather impact, limited range detection



... cannot detect VRUs in non-line-of-sight



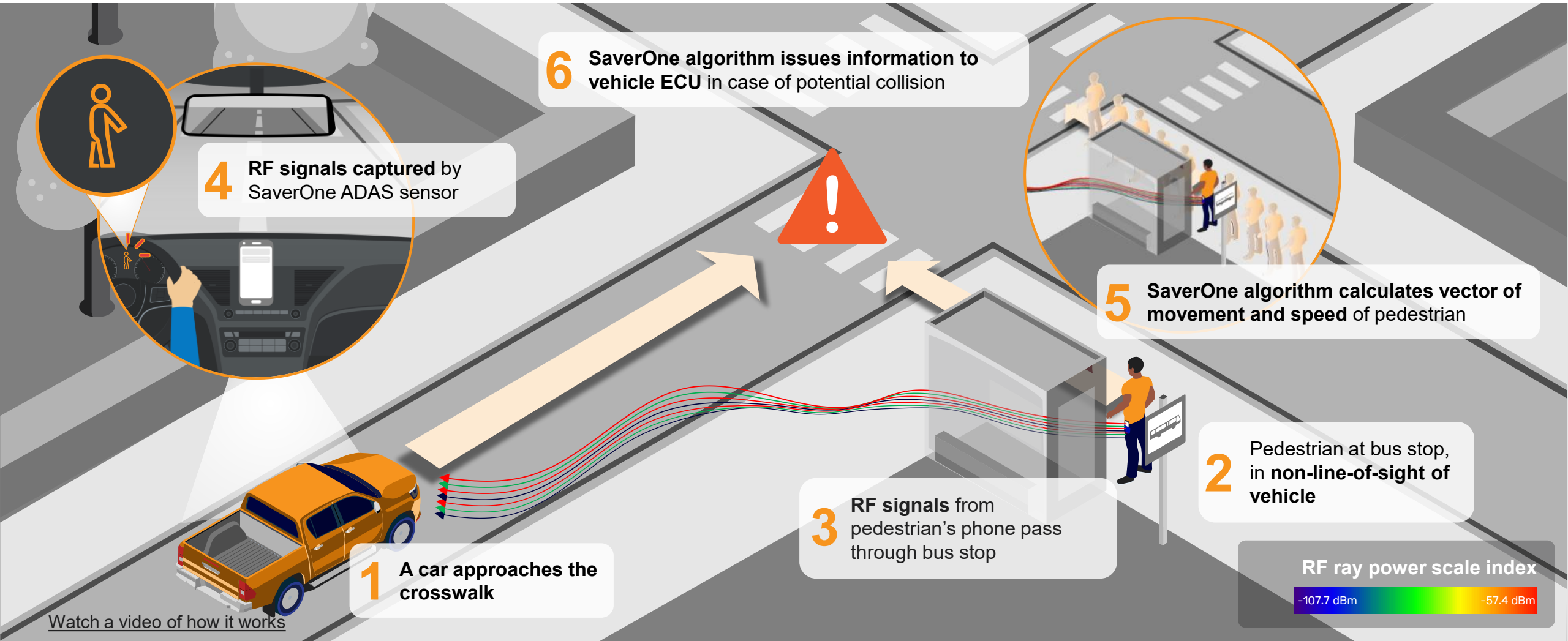
Detection of potential VRU is blocked by bus stop – no information about VRU and potential collision can be provided to driver

“ ” Detection of VRUs is a big problem in bad weather and darkness – current sensor technology cannot address these issues sufficiently

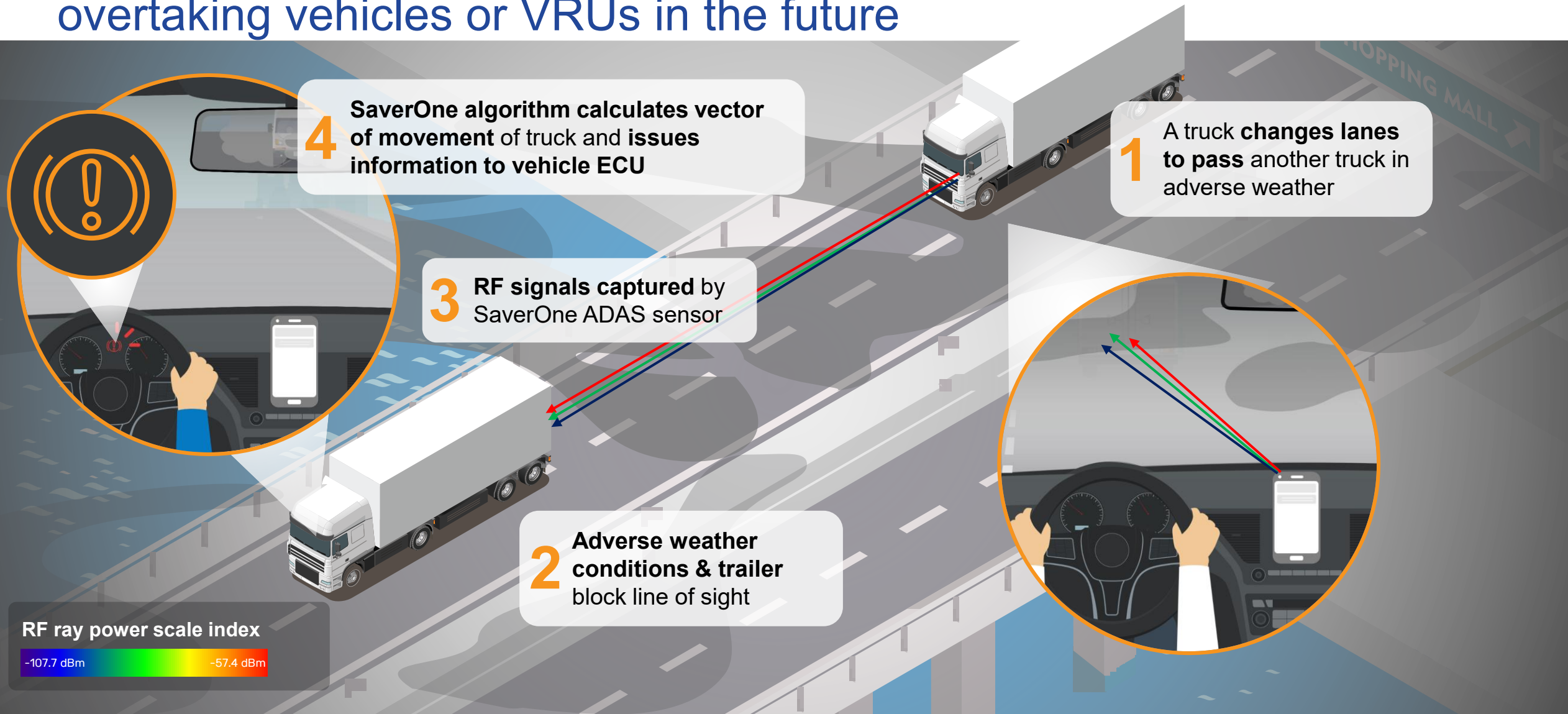
Former VP, Head of LiDAR Segment at Tier-1 supplier

1. Non-line-of-sight

Our radiofrequency-based VRU solution solves this issue & makes roads safer for everyone

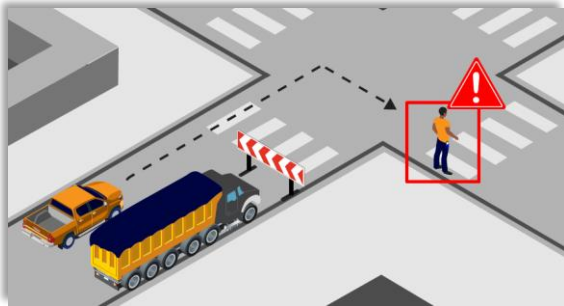


Our radiofrequency-based sensor could even detect rear overtaking vehicles or VRUs in the future



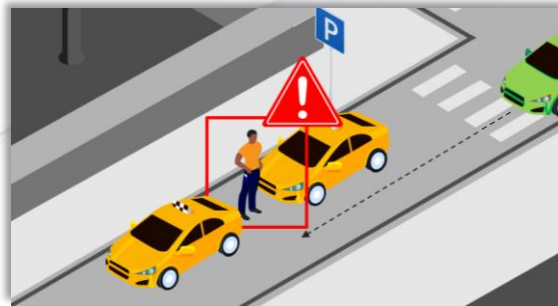
The VRU solution can specifically detect VRUs around corners or hidden by obstacles – and in the future, also rear blindspots

Main use cases



VRUs around corners

Pedestrian approaching road from around the corner, not visible to the driver and not detectable by other sensors



VRUs behind obstacles

Pedestrian emerging between 2 parked cars, not visible to the driver and only detectable by strategically low or highly placed LiDAR systems

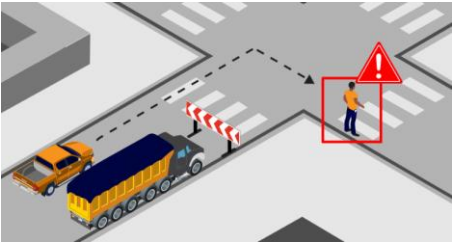
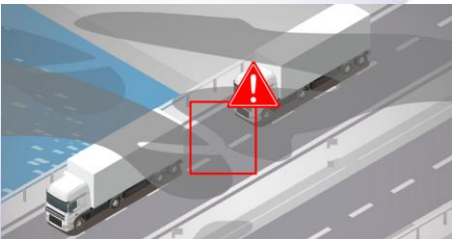
Future use case



Blind spot detection

Detection of cars and VRUs in blind-spots (especially relevant for trucks or in poor weather/ lighting)

No other sensor set-up today can do this – our solution is required to detect VRUs in non-line-of-sight






Safety use case	Individual sensors			Relevant sensor combinations				
	Camera	Radar	LiDAR	RF VRU solution SAVERONE	Radar + camera	Radar + LiDAR + camera	Radar + camera + SAVERONE	Radar + LiDAR + camera + SAVERONE
 VRU in non-line-of-sight	⊗	⊗ ¹	⊗	✓	⊗ ¹	⊗ ¹	✓	✓
 Rear overtaking vehicles²	⊗	⊗	⊗	⊗	⊗	⊗	✓	✓

1. Only basic detection of (moving) VRUs between cars through low-positioned sensors
2. Especially relevant for trucks, given limited availability of rear sensors and large trailers

The VRU sensor complements the existing ADAS sensor suite to detect VRUs in bad weather & lighting and outside-line-of-sight situations

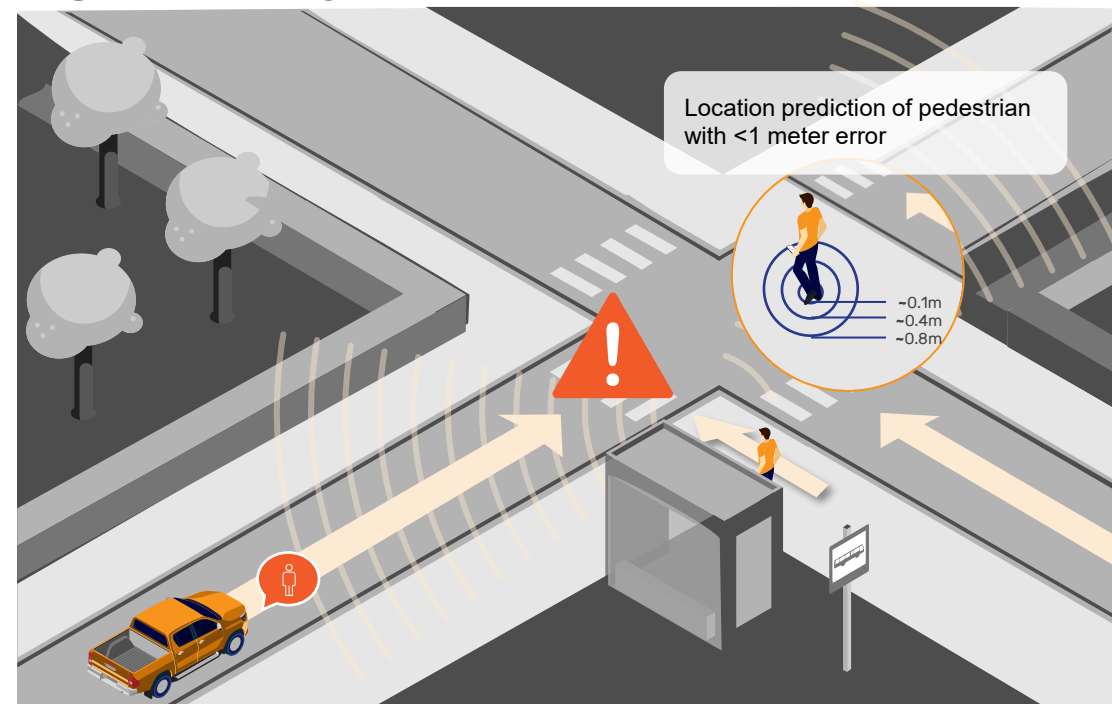
The VRU solution in a nutshell


Technical details

-  Detection, classification, localization, tracking of VRUs and notification of driver in case of potential collision
-  Reception and analysis of radiofrequency signals¹
-  Operating range up to 150 meters
-  Capacity Up to 50 phones
-  High accuracy with <1 meter error²

1. Cellular & Wifi supported (700-3,800 MHz, 5800-5900 MHz BLE)
2. Simulation conducted in Wireless Insite

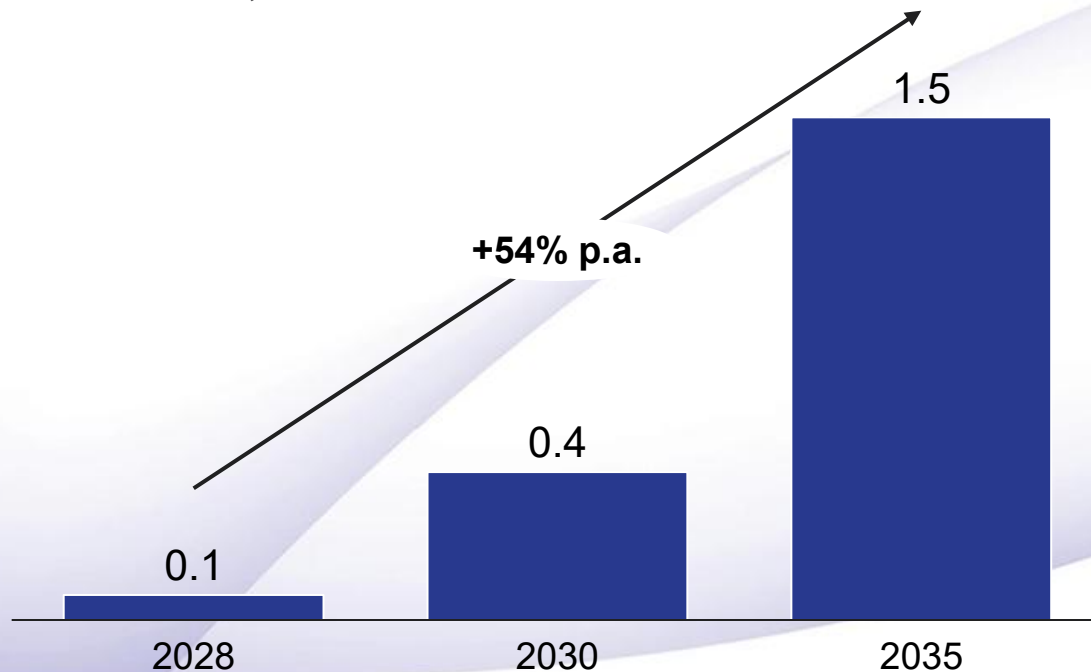
High Accuracy: error <1 meter



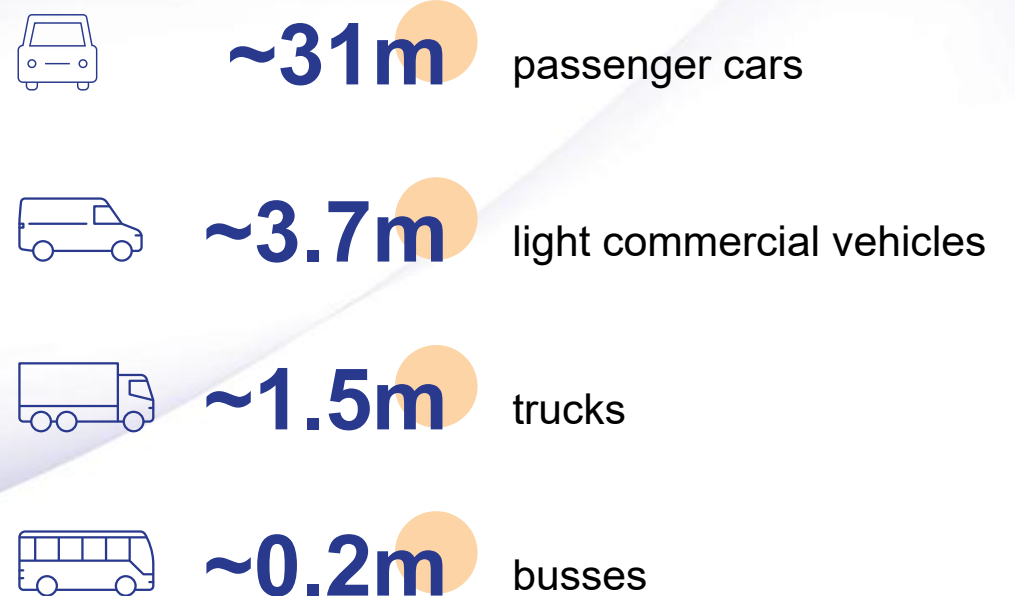
-  Error of algorithm in predicting pedestrian position depends on distance from car (20-50m) and obstacle between pedestrian and car (glass, concrete) – depicted relative to body size, details in appendix

Our VRU solution addresses a new market of ~1.5 bn USD in 2035

Global automotive RF-sensor market for VRU detection¹, in USDbn





























2035 TAM² consists of....



1. Including passenger cars, light commercial vehicles, truck, busses, robo-taxis
2. TAM = Total addressable market

We address core pain points of our customers

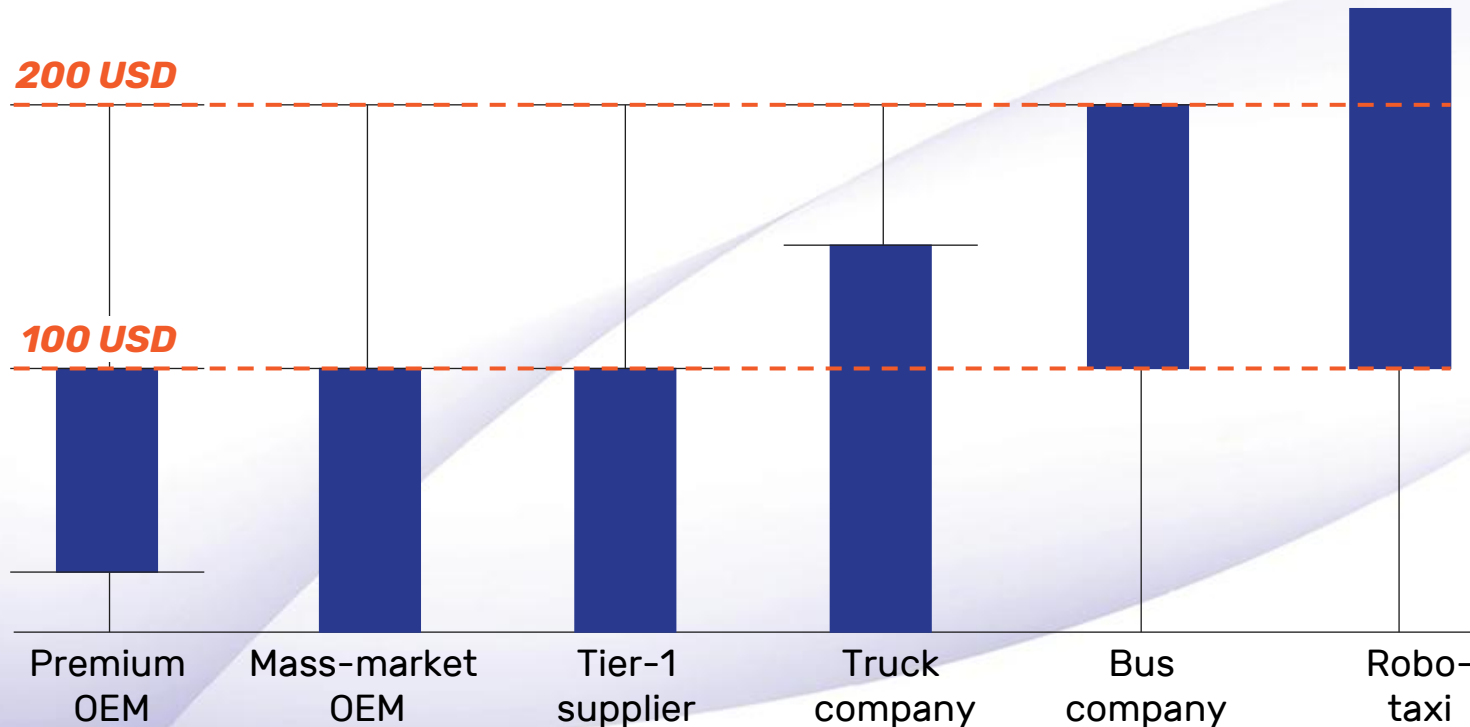
 Strong applicability for customer
  Limited applicability for customer
  No applicability

				
Core value proposition	Passenger car OEMs	Truck & Bus OEMs	Robo-taxis	
Enhanced safety, improving value and selling proposition				
Potential improved safety ratings/ regulatory benefits ¹				
Reduced risk of liability claims ²				
Lower insurance cost				
Optimized vehicle utilization (driving speed of AD ³ potentially limited due to safety)				
Projected take rates from expert survey ⁴	Entry 10-30% 	Volume 20-40%  Premium 50-80% 	40-80% 	~80% 

1. If testing procedures and/or scoring criteria are adjusted
2. In autonomous driving modes
3. AD = Autonomous Driving
4. Based on Expert interview with n=24 experts

Target customers show a high willingness to pay for a new sensor technology like ours

Willingness to pay by customer type, in USD



“If there was a working VRU detection sensor, there would for sure be a willingness to pay, I would estimate ~50 USD”

– *Former Chief Safety Officer at premium OEM*

“If performance, accuracy and reliability are proven, I believe OEMs would be willing to pay ~100 EUR for such a sensor”

– *Former VP, Head of LiDAR Segment at Tier-1 supplier*

The VRU solution could save insurance claim costs of up to ~260+ USD over the lifetime of a passenger car

~260 USD

Insurance claim cost could be saved on average over the lifetime of a vehicle from avoidance of collisions with VRUs

0.064

Collision claims
per vehicle p.a.¹

0.74%

Claims
involving VRU

12y

Over
lifetime

45.3k

Average spend
per claim

Potential upsides



7x



30x

Potential value of up to ~1,875 USD on average for taxis generally given higher utilization and even further upside for robotaxis due to no breaks required

Potential value of up to ~8,400 USD on average in the US given higher cost for VRU accidents with large tail towards high-end (about 1/3 of accidents with costs >600k USD)


cruise e.g., **~8-12mn USD settlement** with a pedestrian hit by robotaxi

1. p.a. = per annum

Note: Rounding of individual numbers

Source: Global tier-1 Management Consultancy

There is no direct competition – our solution is the only one that protects VRUs even if they do not have an app

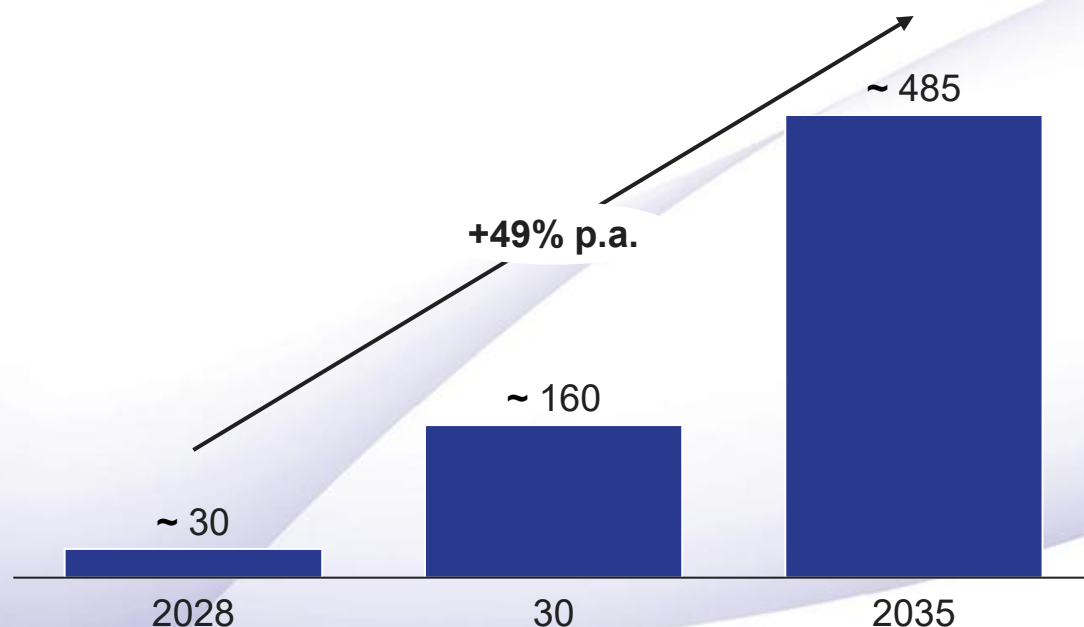
			Competitor 1	Competitor 2
Passive reception of signals	Independent of active communication between two media	✓ Passive radio-frequency signal detection	✗ Active V2X app-based communication	✗ Active V2X app-based communication
Works without an app for the VRU	Independent of installation of specific app or software at VRU-end	✓ No installation required on VRU-end	✗ e.g., specific app, maps apps, or firmware package ¹	✗ Add-on integration into location-based 3 rd party apps
Integrated into vehicle safety features	Could be integrated into specific ADAS features e.g., automatic emergency braking	✓ Deep integration with other ADAS sensors	? Phone-based warning function, potentially with ADAS integration ²	✗ Phone-based warning function only (no ADAS integration)
On track to scale	Active development with tangible plan for strong roll-out	✓ Currently in MVP development	? Pilot phase, testing ended in 2020 due to lack of data/ user coverage	? Low scale, given reliance on SDK ³ integration

1. Based on radio transmitter and receiver
2. Published as communication with engine ECU
3. Software development kit

We have strong ambitions and estimate a revenue potential of >480m USD by 2035

Business plan

Revenues, in USDm



2028

First revenues¹

11m

Sensors sold 2035

~12%

EBITDA margin 2035

2030

Profitability reached²

~30%

Gross margin 2035

51M

NPV³, in USD

1. From premium passenger cars and commercial vehicles

2. Measured in EBITDA

3. Based on cash flows until 2035, excl. terminal value. WACC of 8.5% used for discounting cashflows

We have developed the IP and are now looking for a partner to complement our skills with technical & commercial expertise



SAVERONE

- ✓ Product vision and specification
- ✓ Intellectual property and algorithm development
- ✓ Key talent

Strategic partner

- ✓ Technical expertise (e.g., chip design, sourcing, industrialization, manufacturing, logistics)
- ✓ Commercial expertise (e.g., global OEM relationships, sales channels, automotive grade process excellence)
- ✓ Financial contribution

We are already demonstrating the technology, and will get the product MVP to customers in 2026 – together with you

We have already achieved a lot...

... and will continue at full speed

mid-2026

MVP demo to customers





















1. Expert interview



APPENDIX

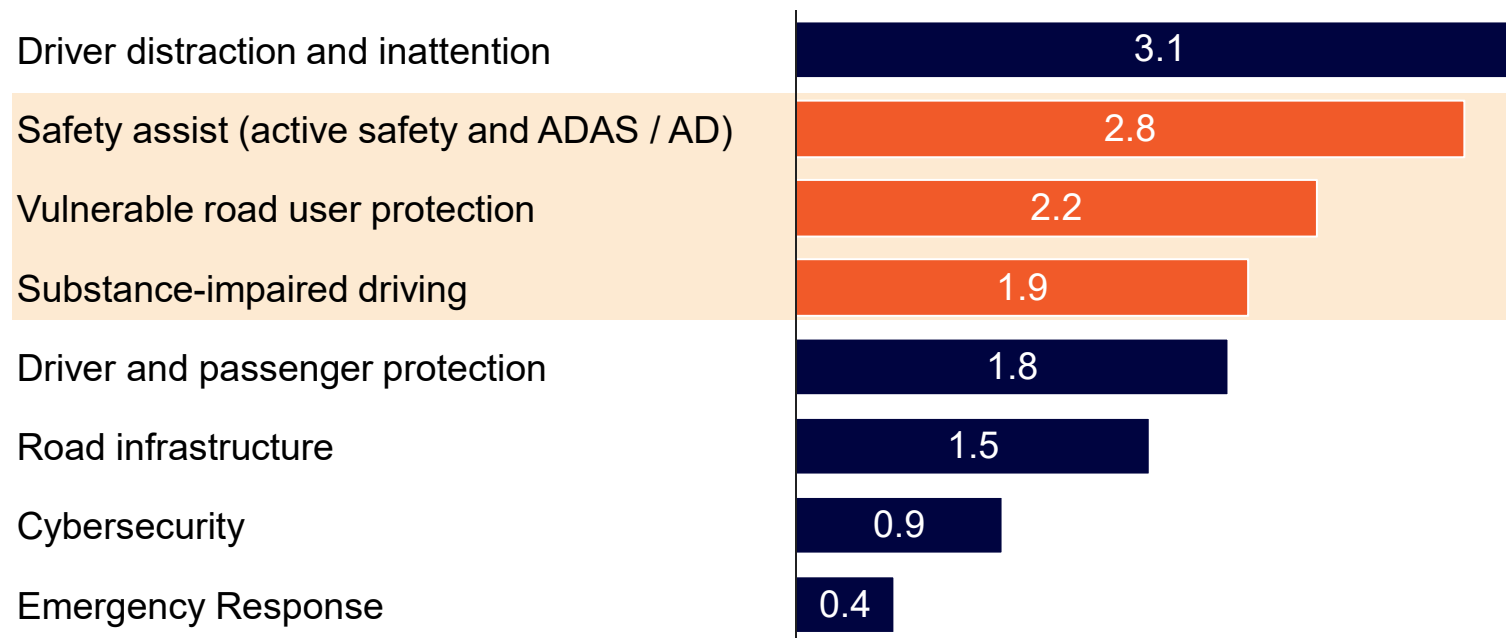
Our product is addressing the market for active safety and ADAS/AD

	Passive Safety	Active Safety	<i>Focus of our VRU solution</i> ADAS/Autonomous Driving (AD)	
 Main objective	Mitigation of impact of collisions for occupants and VRUs	Avoidance of collisions	Enhanced comfort	
 SAE levels	n/a	0	1 2 2+ 3 4 5	
 Examples of systems Occupants	 Airbag	 Automatic emergency braking system Car-to-Car	 Adaptive Cruise Control	
	 Safety belt	 Driver Distraction Monitoring	 Lane Centering	
	 Chassis construction	 Blind Spot Detection		
	 Fuel Pump Shut-Off Switch	 Electronic stability program		
 Examples of systems VRU	 Chassis construction to reduce impact	 Automatic emergency braking system Cyclist & Pedestrian	 L2+ or L4 in urban environments	
	 eCall system ¹			

1. For both VRUs and occupants

Our VRU solution addresses the most important unsolved problems in vehicle safety






















Largest unsolved problems in vehicle safety today, (5 being highest)



Our VRU solution addresses the most important problems in vehicle safety through:

Improving existing ADAS systems
&
Providing resilient VRU detection

Simulation error of VRU solution <1m for different obstacles

Car Distance meter	Pedestrian's progress start, meter	Pedestrian's progress end, meter	Glass Pedestrian distance estimation error, meter	Concrete Pedes- trian distance estimation error, meter
-50	4.4 	4.0	 0.84	 0.44
-45	4.0 	3.6	 0.15	 0.15
-40	3.6 	3.2	 0.12	 0.14
-35	3.2 	2.8	 0.18	 0.18
-30	2.8 	2.4	 0.15	 0.14
-25	2.4 	2.0	 0.46	 0.13
-20	2.0 	1.6	 0.45	 0.46

Simulation error <1m for distances up to 50 meters¹ for both materials tested blocking line of sight from driver's car (glass and concrete)

1. Simulation conducted in Wireless Insite

VRU detection through the sensor follows a 5-step process to ensure collision avoidance



Detection

Detection of mobile signals through vehicle-integrated sensors in real-time

Detection of phone signals along whole RF-spectrum
(no requirement for specific signal)



Classification

Filtering and classification of RF-signals to identify number of source-entities/individuals (bandwidth)



Localization

Calculation of location of phone/individual based on RF-signal vectors through algorithm



Tracking

Tracking of speed and direction of individual signals

Filtering of vectors not relevant to tracking

Additional feature:
data usage can be estimated, proxying intensity of activity/distracted of individual



Notification

Notification of vehicle/driver about potential VRU collision, e.g., through visual, audio, vibration alert, or integrated braking system

Activation of AEB or AES